

The Self-Driving Network

From vision to execution

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Self-Driving Cars

Five steps towards full autonomy

Functions to be automated:

- Gears
- Brakes
- Speed control
- Lane control/change
- Obstacle recognition and avoidance
- ...

Full-time performance by the human driver of all aspects of the dynamic driving task

MANUAL DRIVING

Driving assistance of either steering or acceleration/ deceleration; human is expected to do all other driving tasks

DRIVE ASSISTANCE

1

Mode specific execution of both steering and accel/ deceleration; human is expected to do all other driving tasks

PARTIAL AUTOMATION

2

CONDITIONAL AUTOMATION

3

Mode specific performance of all aspects of the driving task, with the expectation that the human will take over if asked to intervene

HIGH AUTOMATION

4

Mode specific performance of all aspects of the driving task, even if the human does not take over if asked to intervene, in many driving modes

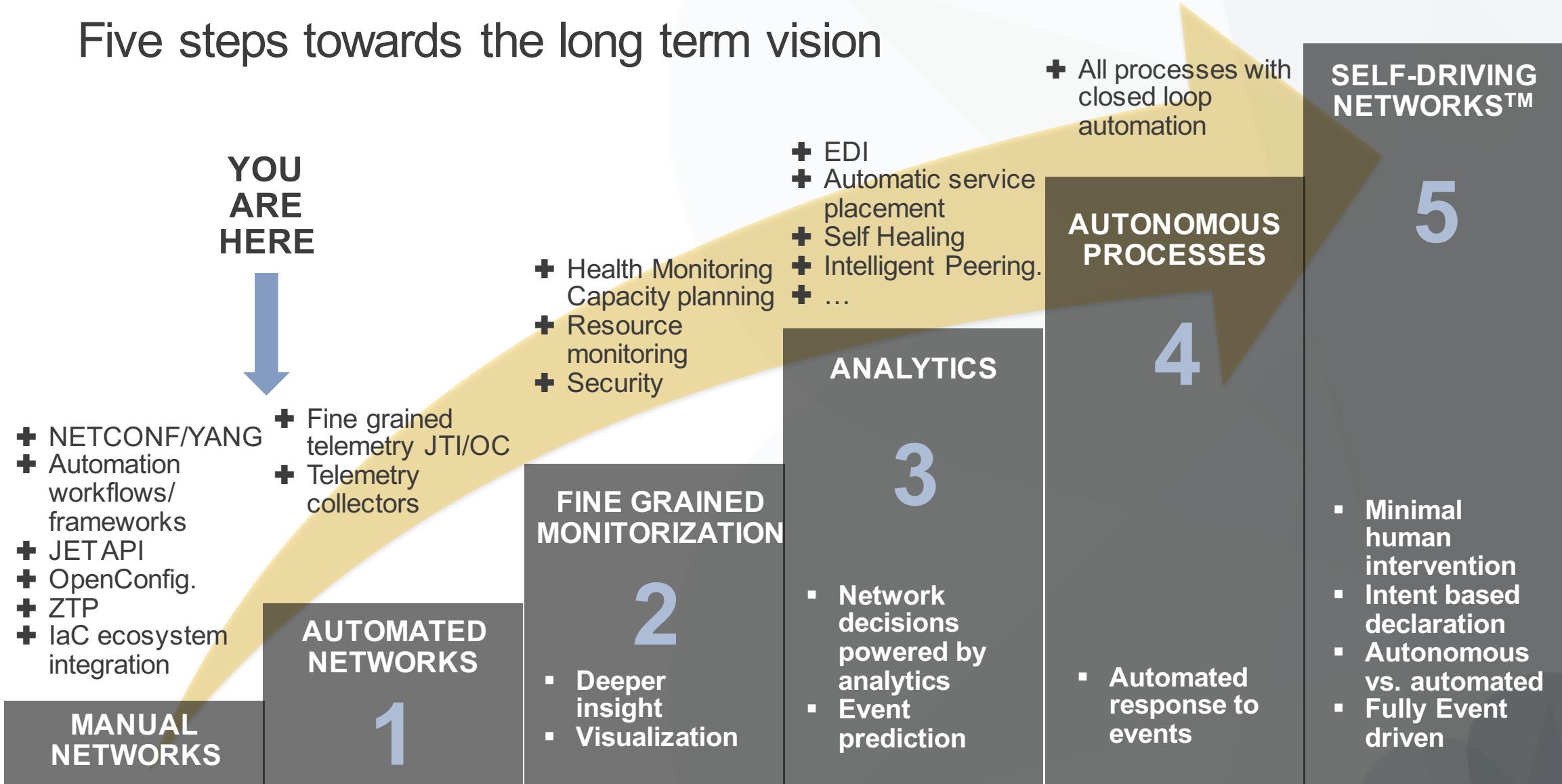
FULL AUTOMATION

5

Full-time performance of all aspects of the driving task under all driving/road conditions

The Self-Driving Network™

Five steps towards the long term vision



Intent – Declarative: Say what you want, not how

- ✓ Intent is non-specific
unnecessary details avoided



- ✓ Intent is stable
immune to network changes

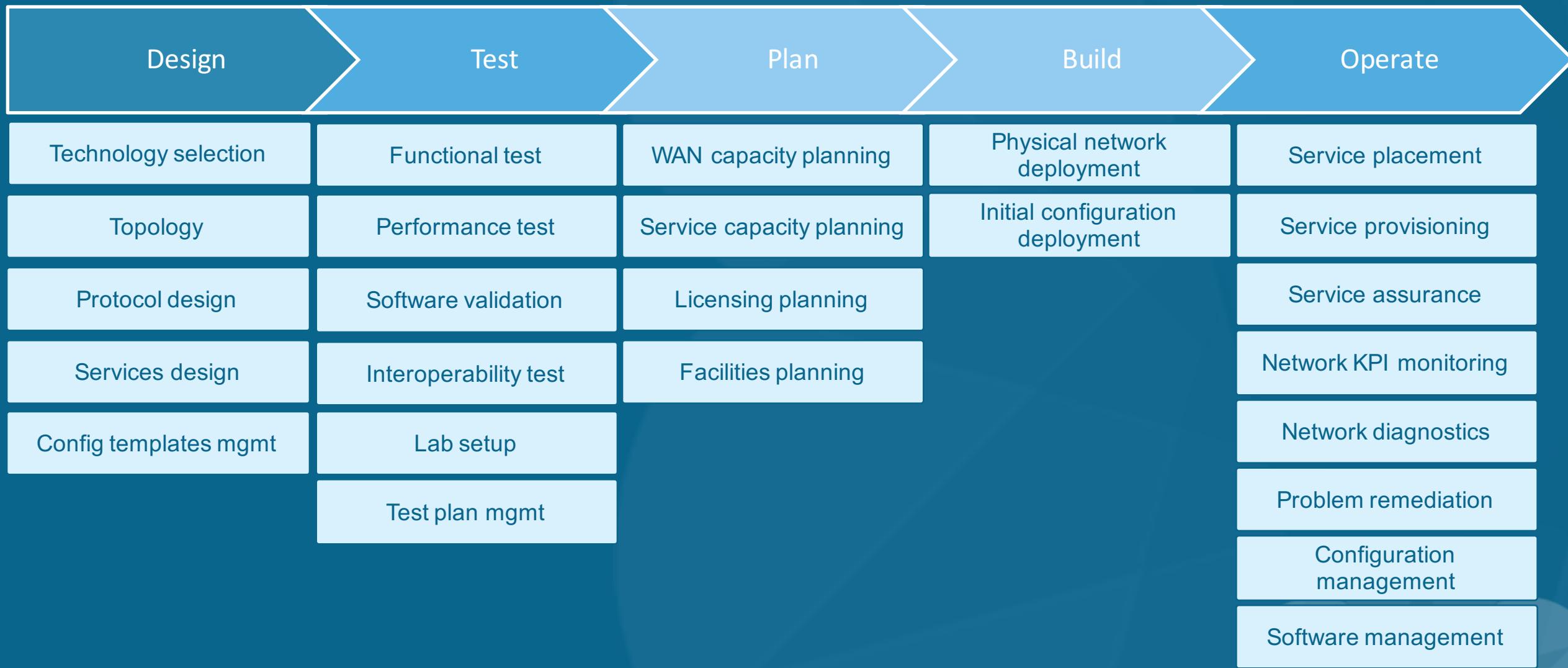


- ✓ Intent provides context
user service more meaningful

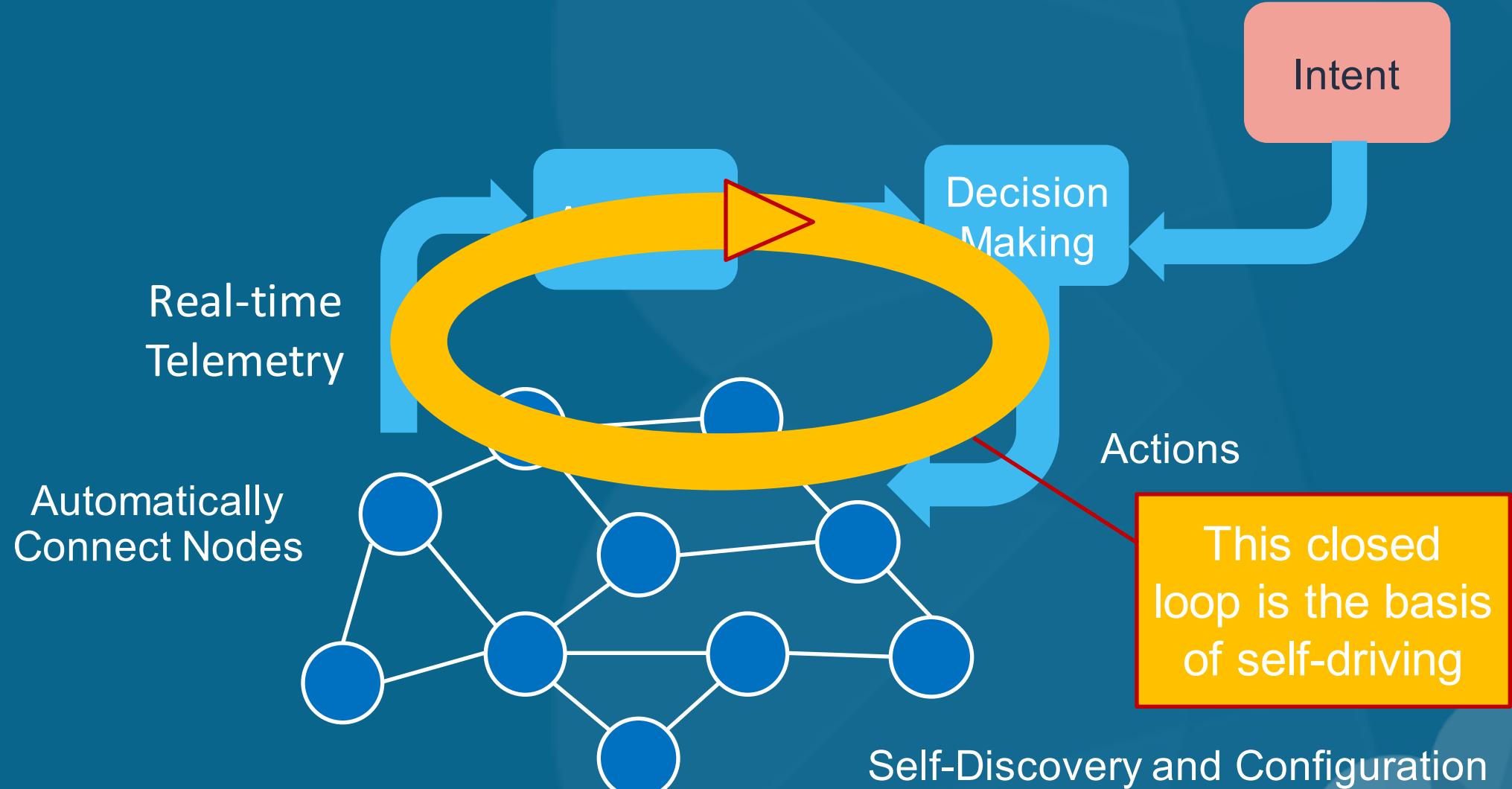


The Self-Driving Network implementation

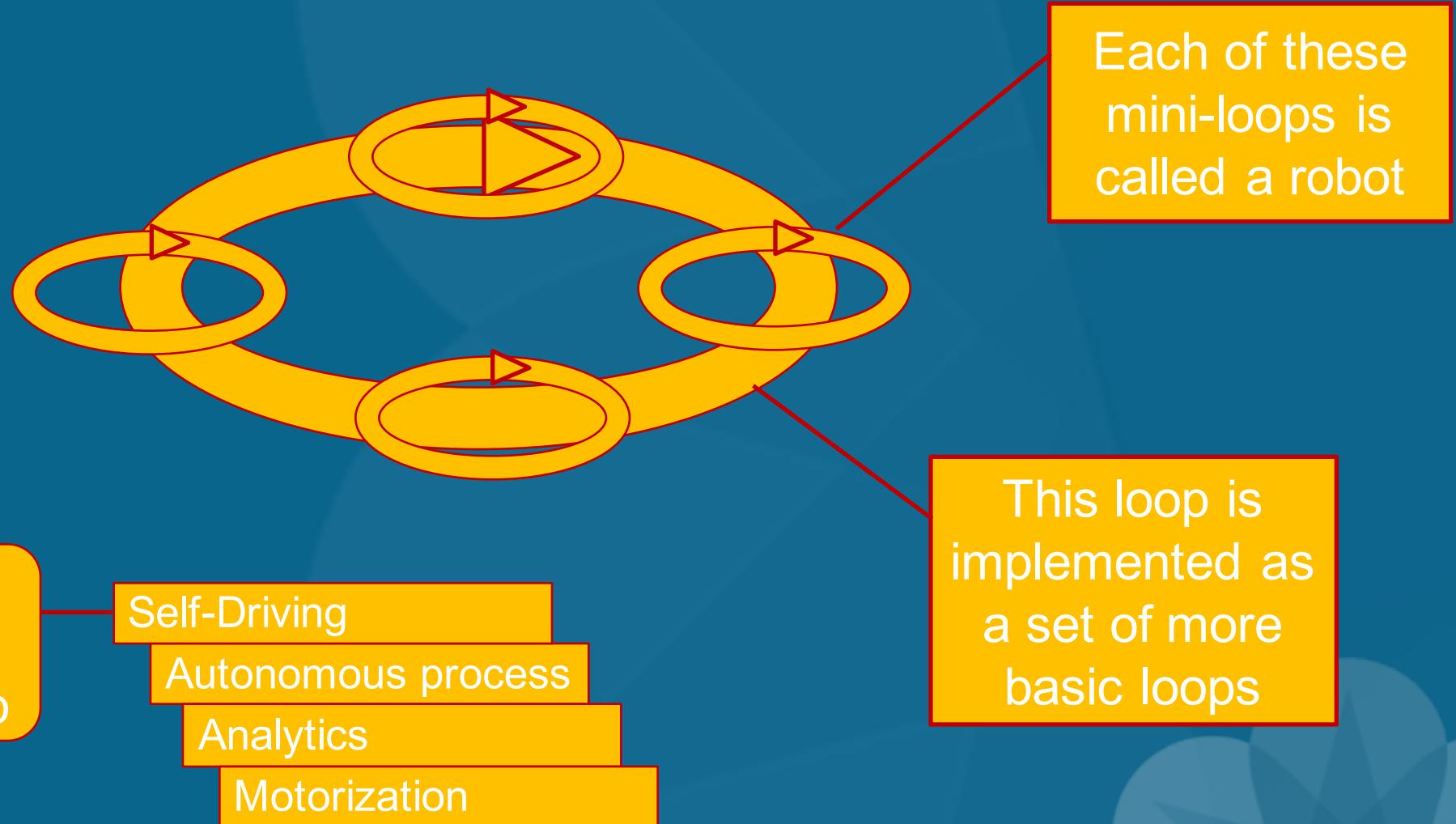
Processes that require self-driving



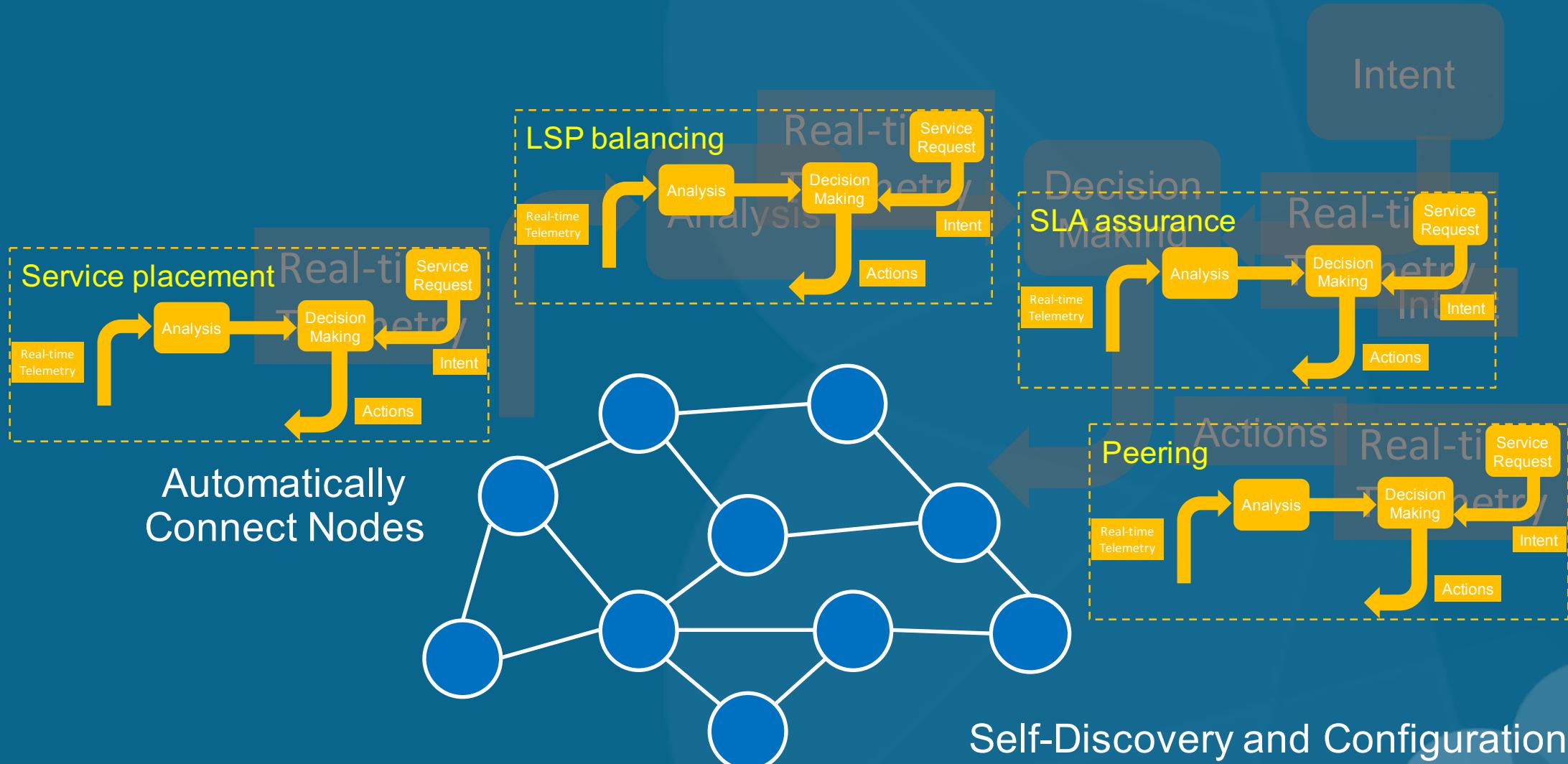
Architecture of the Self-Driving Network



Implementing the Self-Driving Network



Robotized Functions in the Self-Driving Network



FIRST ROBOT: SERVICE PLACEMENT

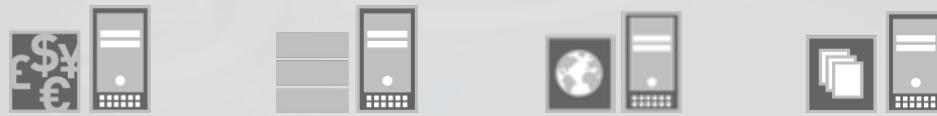
which device should offer a given service?

- 1 **Specify Service Intent** Don't worry about where it will be
- 2 **Where best to place the service?** Let the controller work this out
- 3 **Things change: is placement still optimal?** Streaming real-time data
- 4 **Service Motion: move service to a new location** Update service in real-time

Break the mold! Update service placement often, to keep it optimal

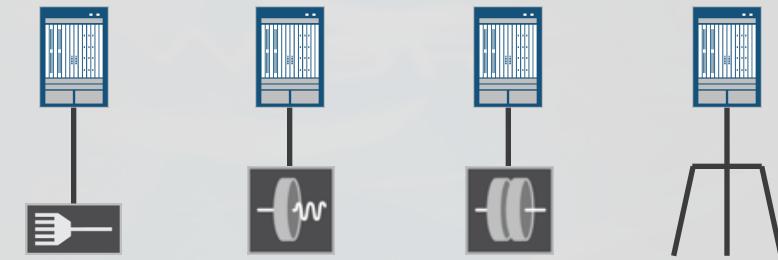
ANALOGY: Compute Orchestration vs Service Orchestration

OLD: Same (or very similar) servers
running **dedicated** apps



Finance DB Web Apps

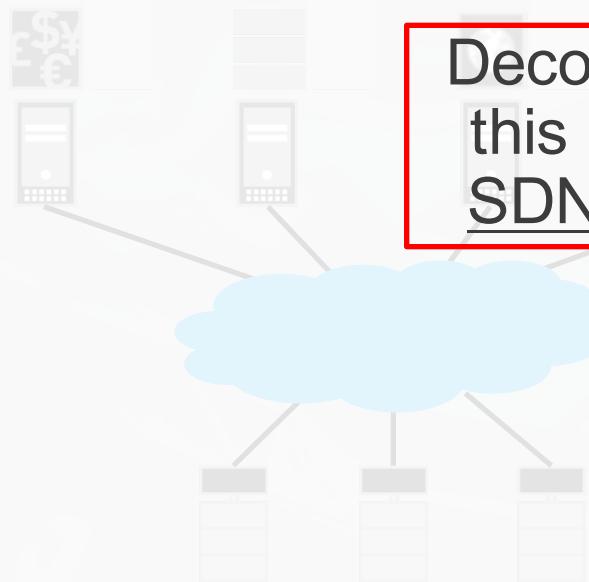
OLD: Same (or very similar) routers
running **dedicated** services



BNG CMTS BizPE Peering

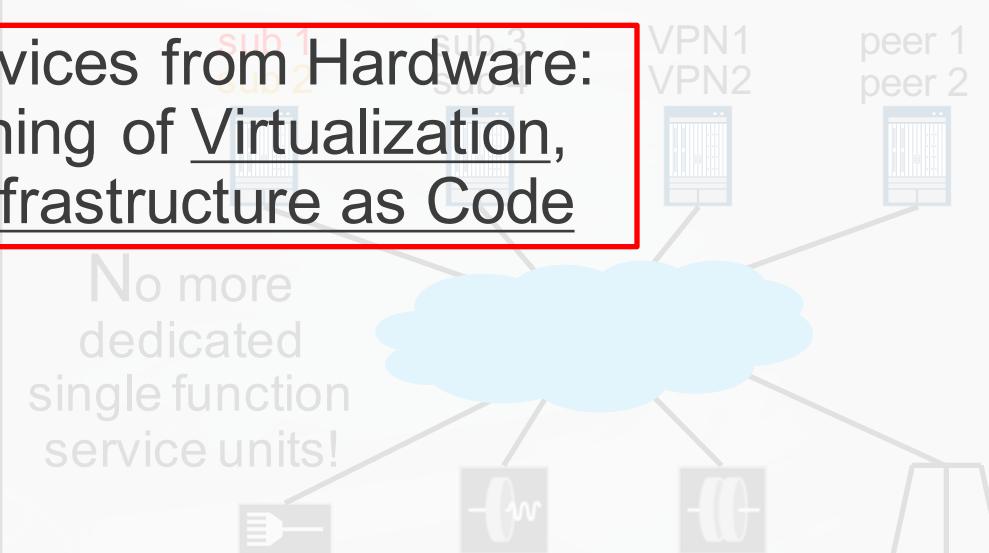
ANALOGY: Compute Orchestration vs Service Orchestration

NEW: Apps decoupled from servers;
storage available to all servers;
servers are now identical



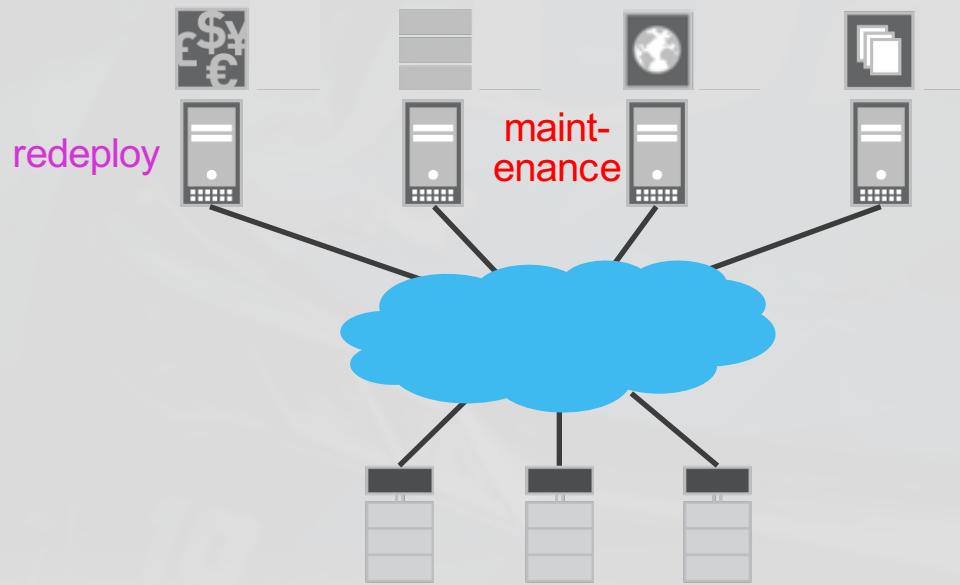
Decoupling Apps/Services from Hardware:
this is the True Meaning of Virtualization,
SDN, NFV, Agility, Infrastructure as Code

NEW: Services are decoupled from routers;
access devices available to all routers;
routers are now identical

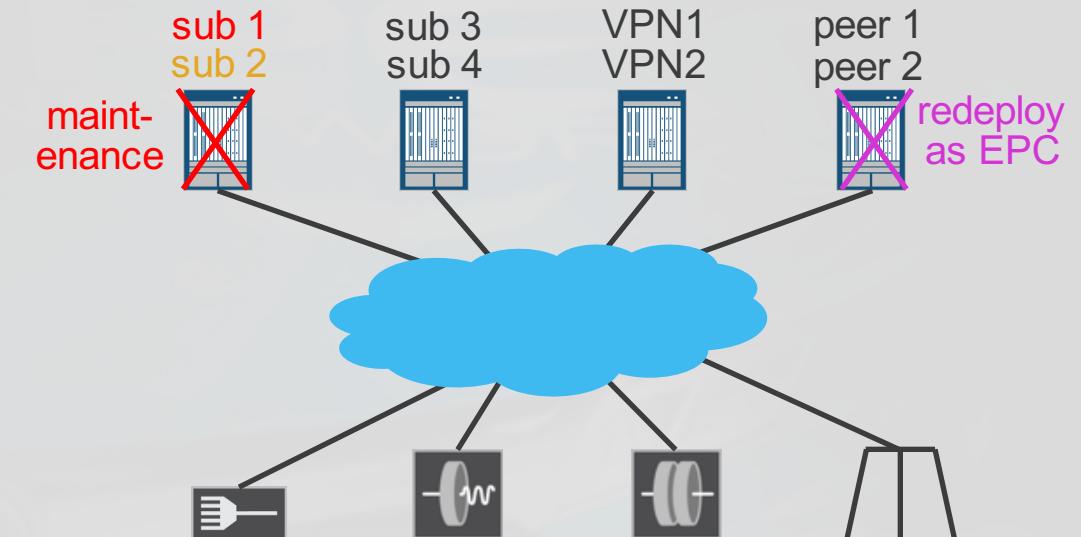


ANALOGY: Compute Orchestration vs Service Orchestration

NOW POSSIBLE: “vMotion” of individual apps across servers; app placement is now a thing



NOW POSSIBLE: “SMotion” of individual services across routers; service placement is now a thing



Peer Bot

Simplifying Peering Across Internet Exchange

Business Goals

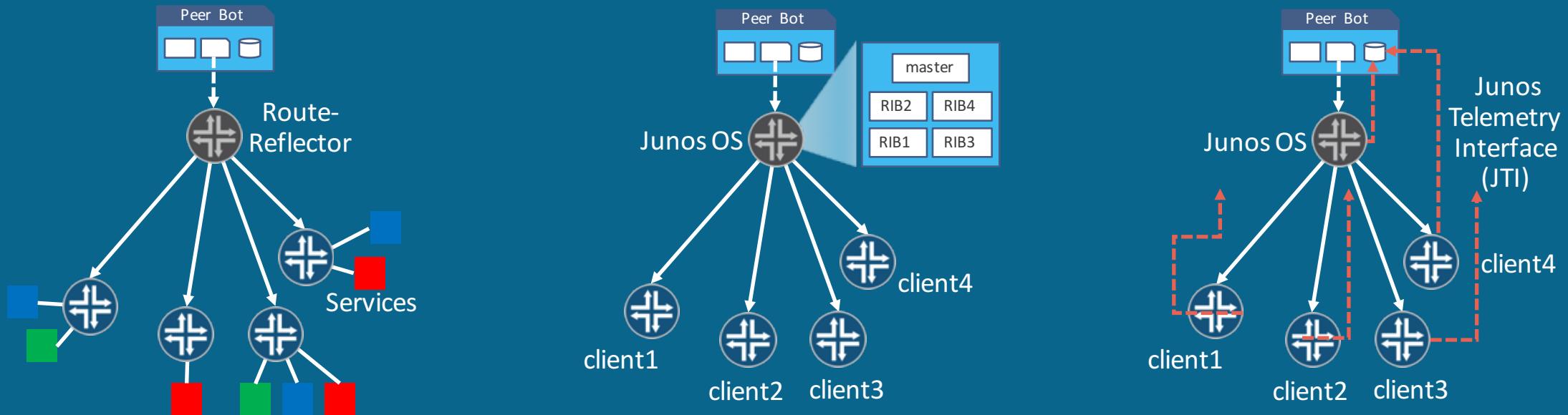
- Optimize Peering costs and application experience

Customer Requirements

- Seamless Internet Exchange Peering Experience
- On-Demand Scaling and Interconnection
- Support Self-Care Portal
- Design, Build and Operate World-class Networks

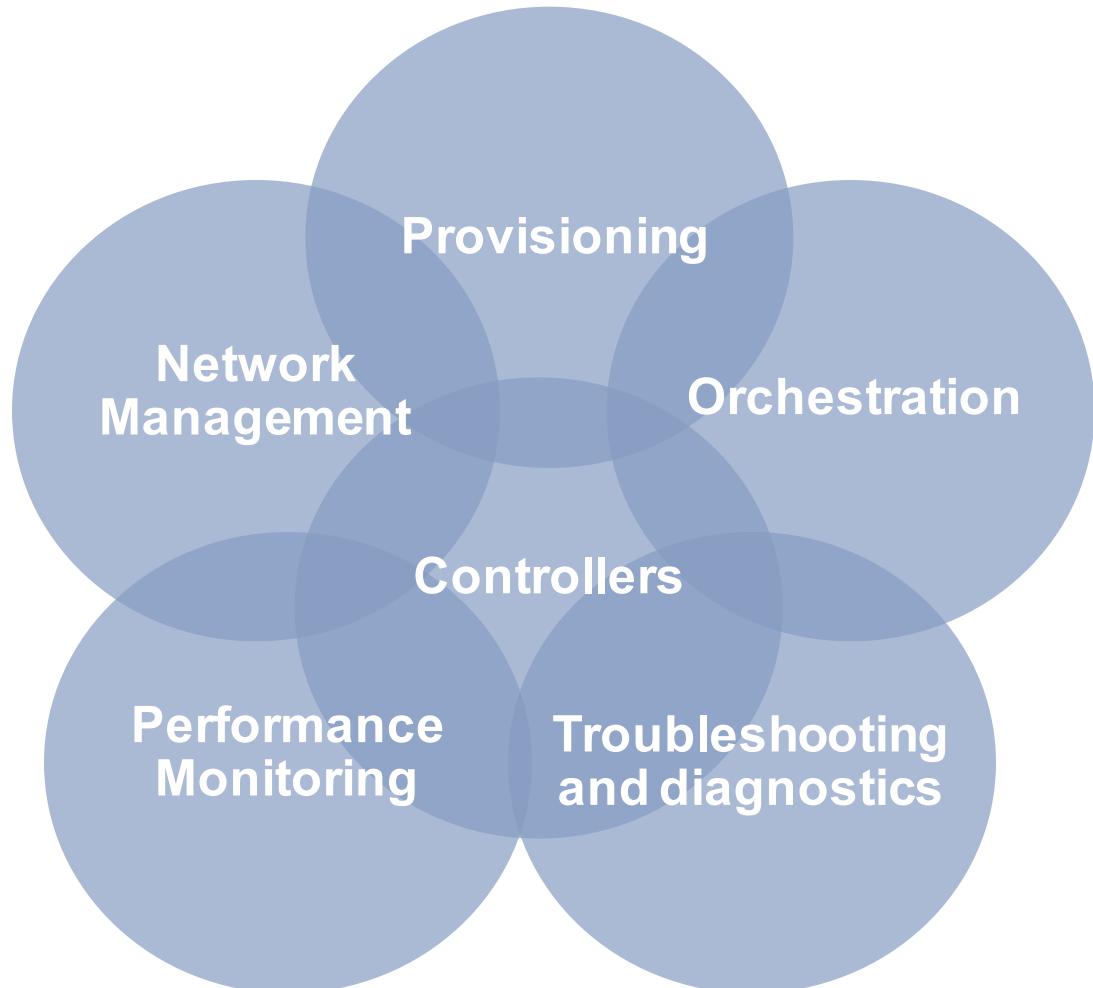
Peer Robot Benefits

- Seamless Add, Modify, and Remove Peering Points
- Dynamically Establish Peering Policy
- Simplify Network Operations by as much as 800%
 - Adding a new peer 8x faster than via CLI
 - Eliminate complex policy enforcement factorially (N!)
 - View the number of peering routes and bandwidth in real-time

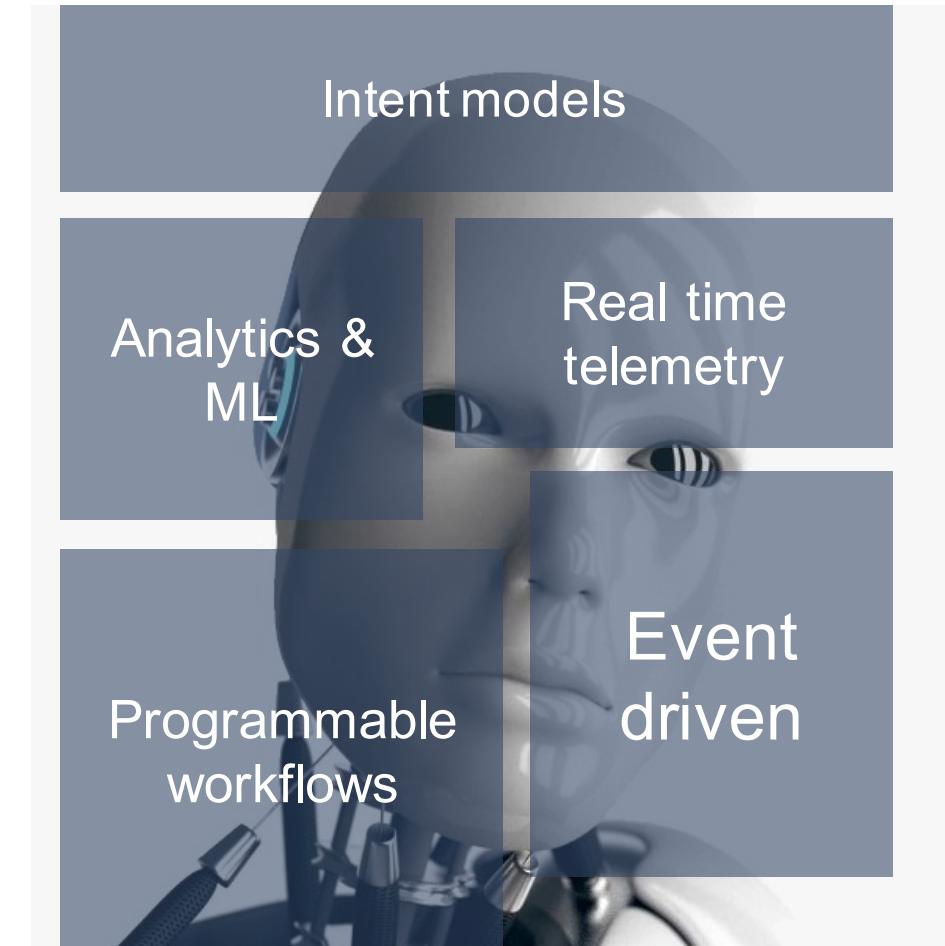


Blurring frontiers...in the Self-Driving Network

Today's network and service management tools



Key new attributes



From network management applications ...

... into Network Robots

Conclusion

A Self-Driving Network may seem a hard (nearly impossible!) task

1. Specify requirements declaratively as intent
2. Divide and conquer – break it down to manageable pieces

Robotizing a function enables new capabilities

- Automating service placement gives you “S-Motion”

Robotizing peering dramatically reduces complexity

- The peer robot makes peering dynamic and responsive

Thank you

Visit our booth to see
the peer robot demo!