

# The Self-Driving Network

## From vision to execution

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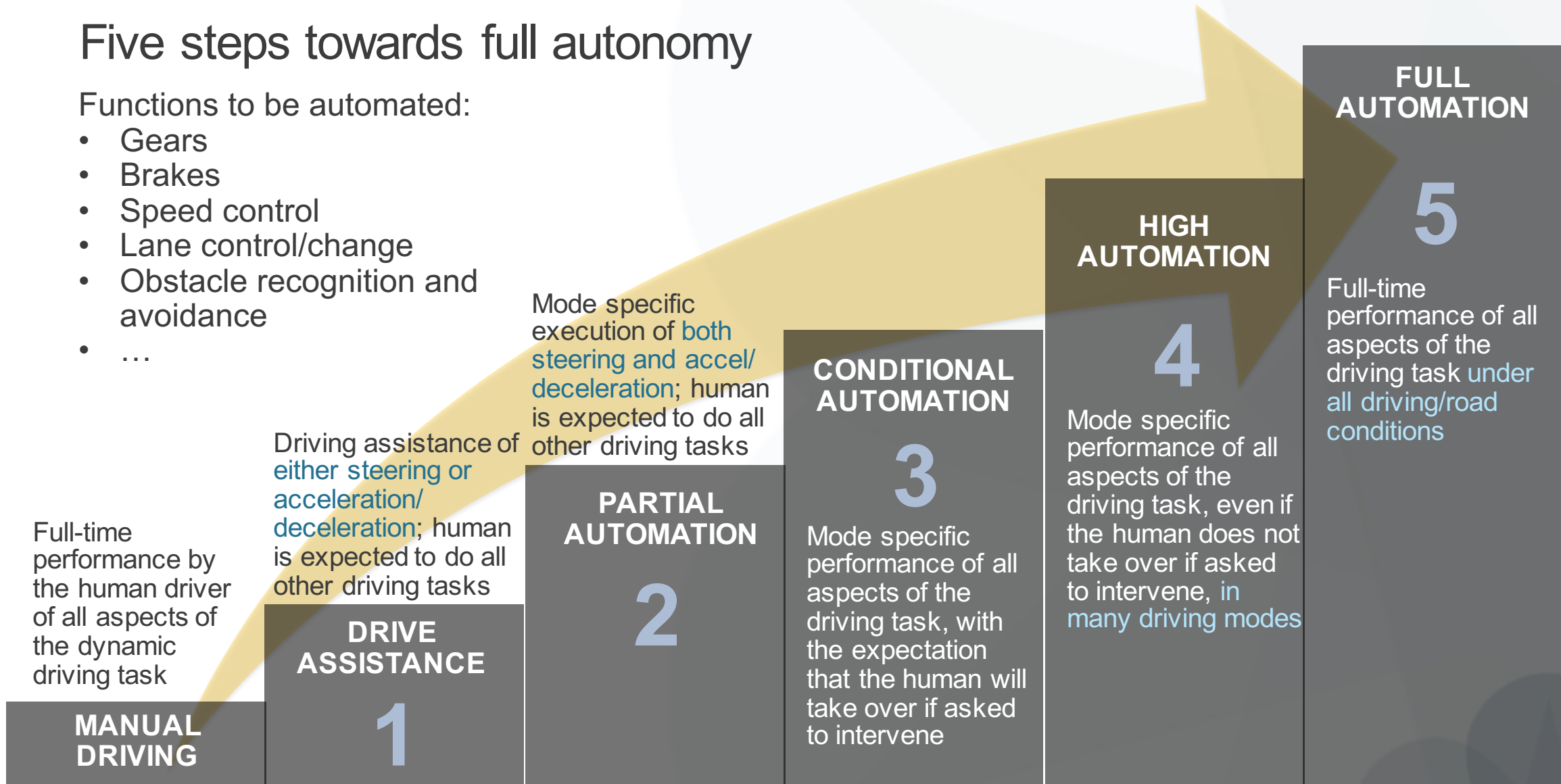
Kireeti Kompella, CTO Engineering

# Self-Driving Cars

## Five steps towards full autonomy

Functions to be automated:

- Gears
- Brakes
- Speed control
- Lane control/change
- Obstacle recognition and avoidance
- ...



# The Self-Driving Network™

Five steps towards the long term vision

**YOU  
ARE  
HERE**



- + NETCONF/YANG
- + Automation workflows/frameworks
- + JET API
- + OpenConfig.
- + ZTP
- + IaC ecosystem integration

- + Fine grained telemetry JTI/OC
- + Telemetry collectors

- + Health Monitoring
- + Capacity planning
- + Resource monitoring
- + Security

- + EDI
- + Automatic service placement
- + Self Healing
- + Intelligent Peering.
- + ...

- + All processes with closed loop automation

**MANUAL  
NETWORKS**

**1**

**AUTOMATED  
NETWORKS**

**FINE GRAINED  
MONITORIZATION**

**2**

- Deeper insight
- Visualization

**ANALYTICS**

**3**

- Network decisions powered by analytics
- Event prediction

**AUTONOMOUS  
PROCESSES**

**4**

- Automated response to events

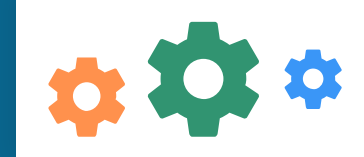
**SELF-DRIVING  
NETWORKS™**

**5**

- Minimal human intervention
- Intent based declaration
- Autonomous vs. automated
- Fully Event driven

# Intent – Declarative: Say what you want, not how

✓ Intent is non-specific  
unnecessary details avoided



✓ Intent is stable  
immune to network changes

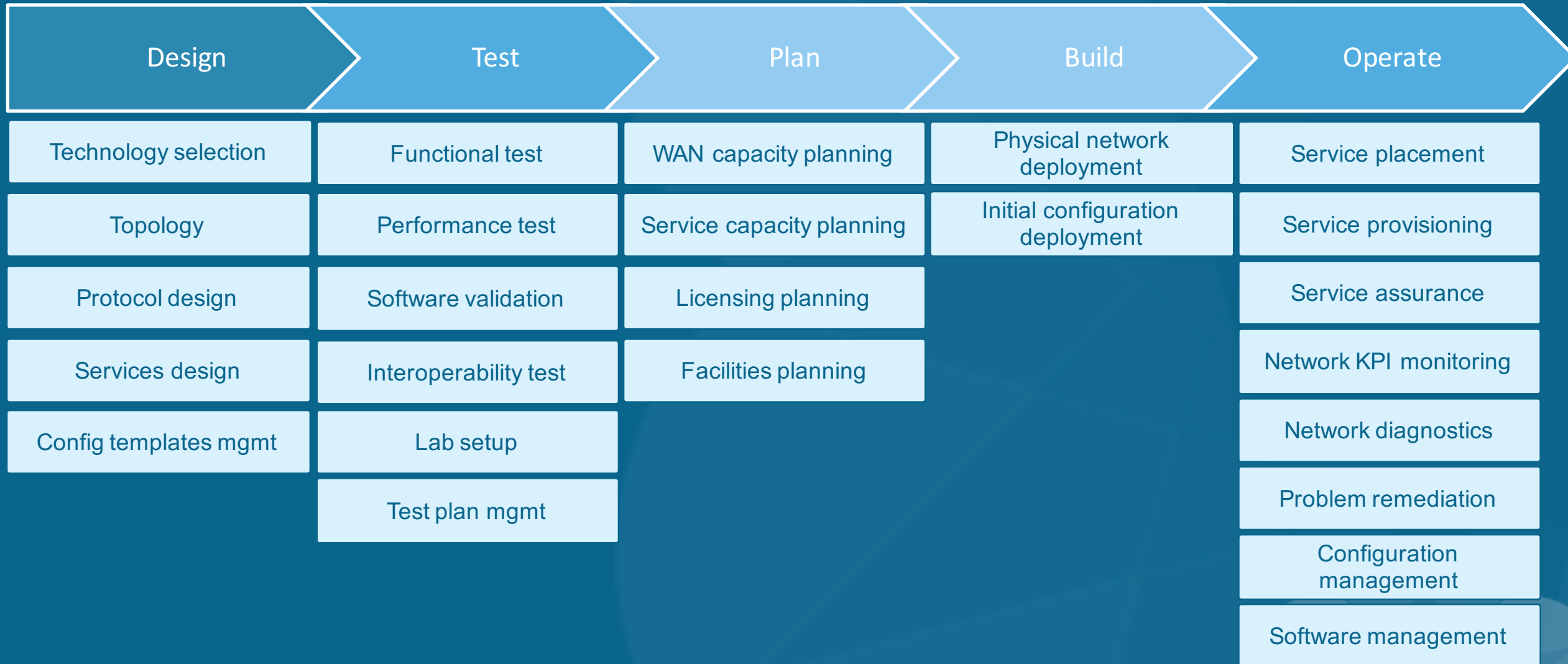


✓ Intent provides context  
user service more meaningful



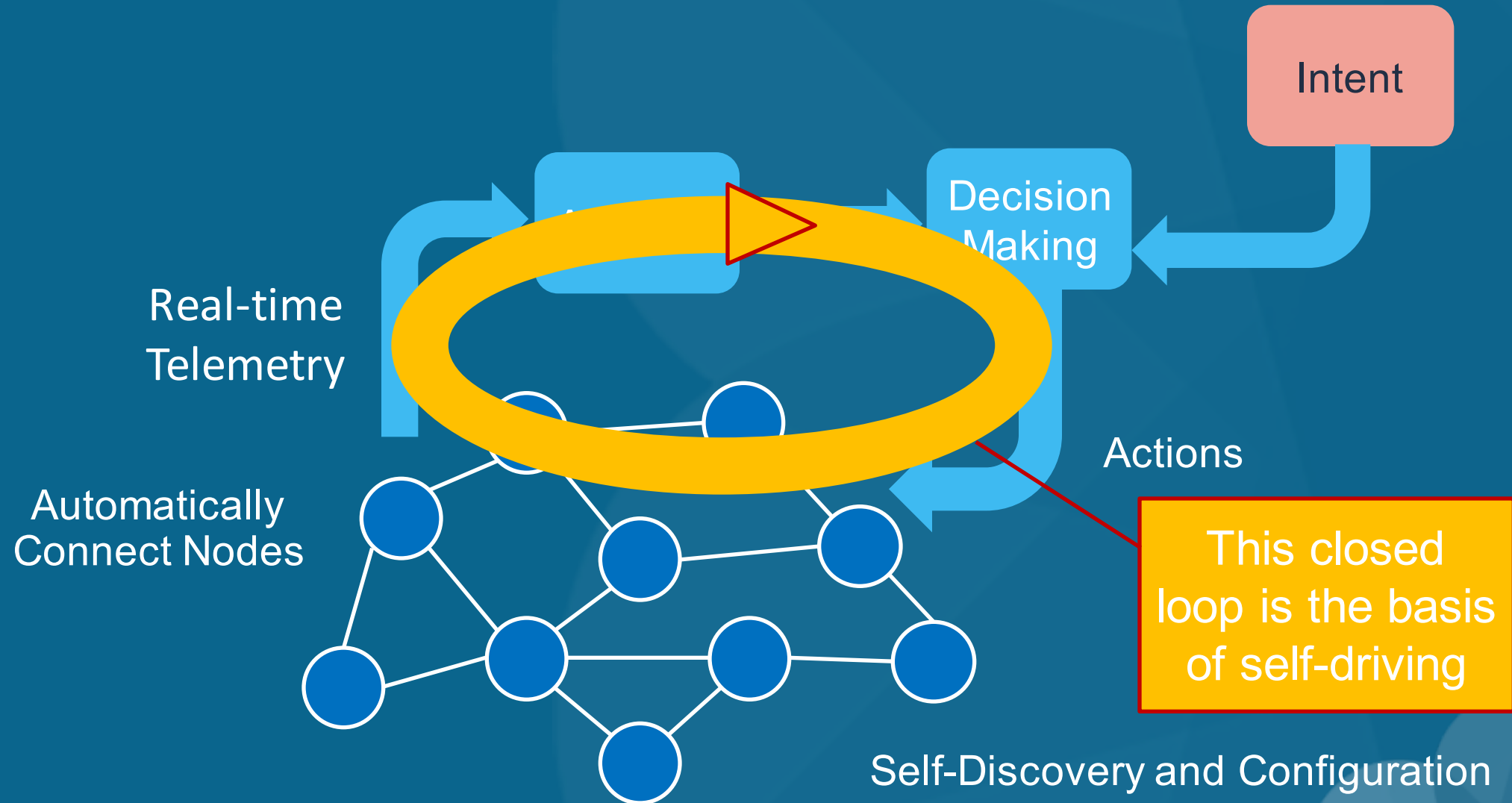
# The Self-Driving Network implementation

## Processes that require self-driving

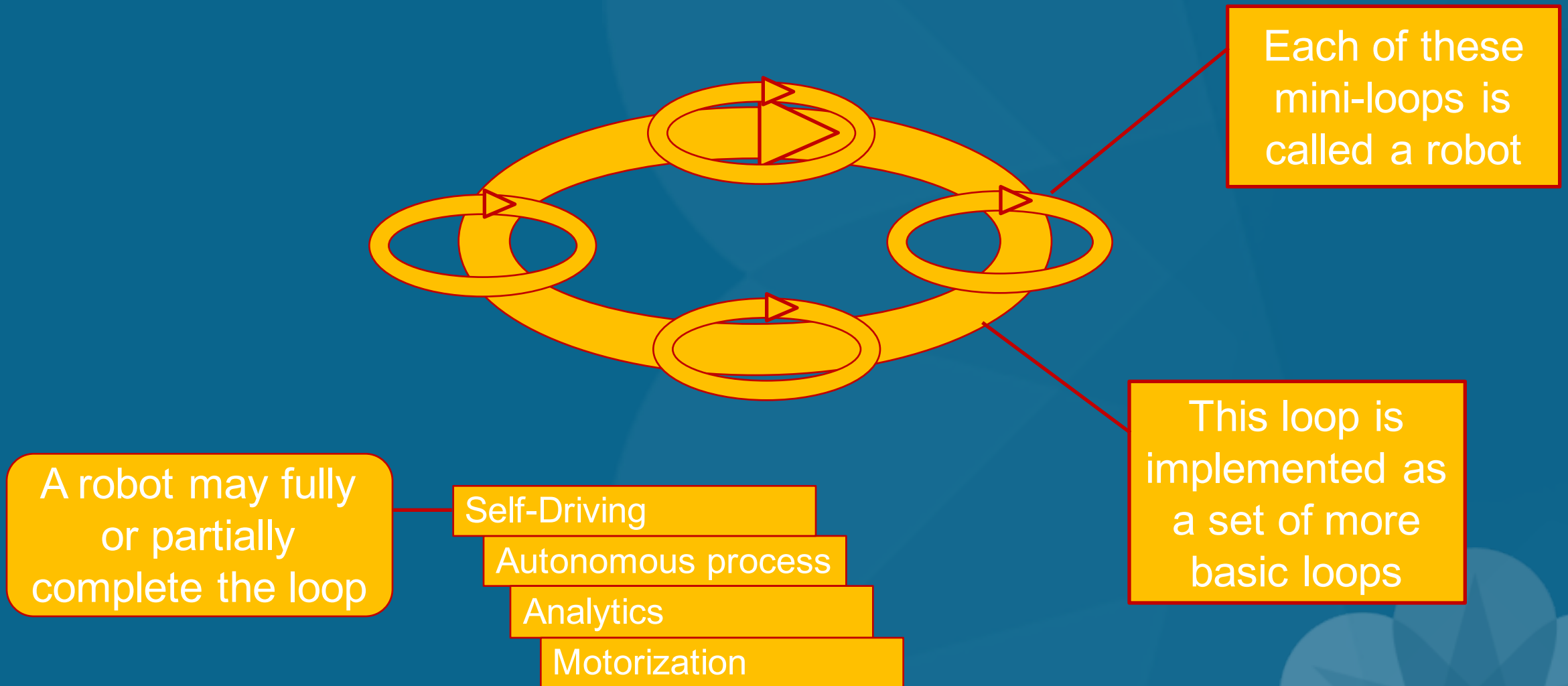




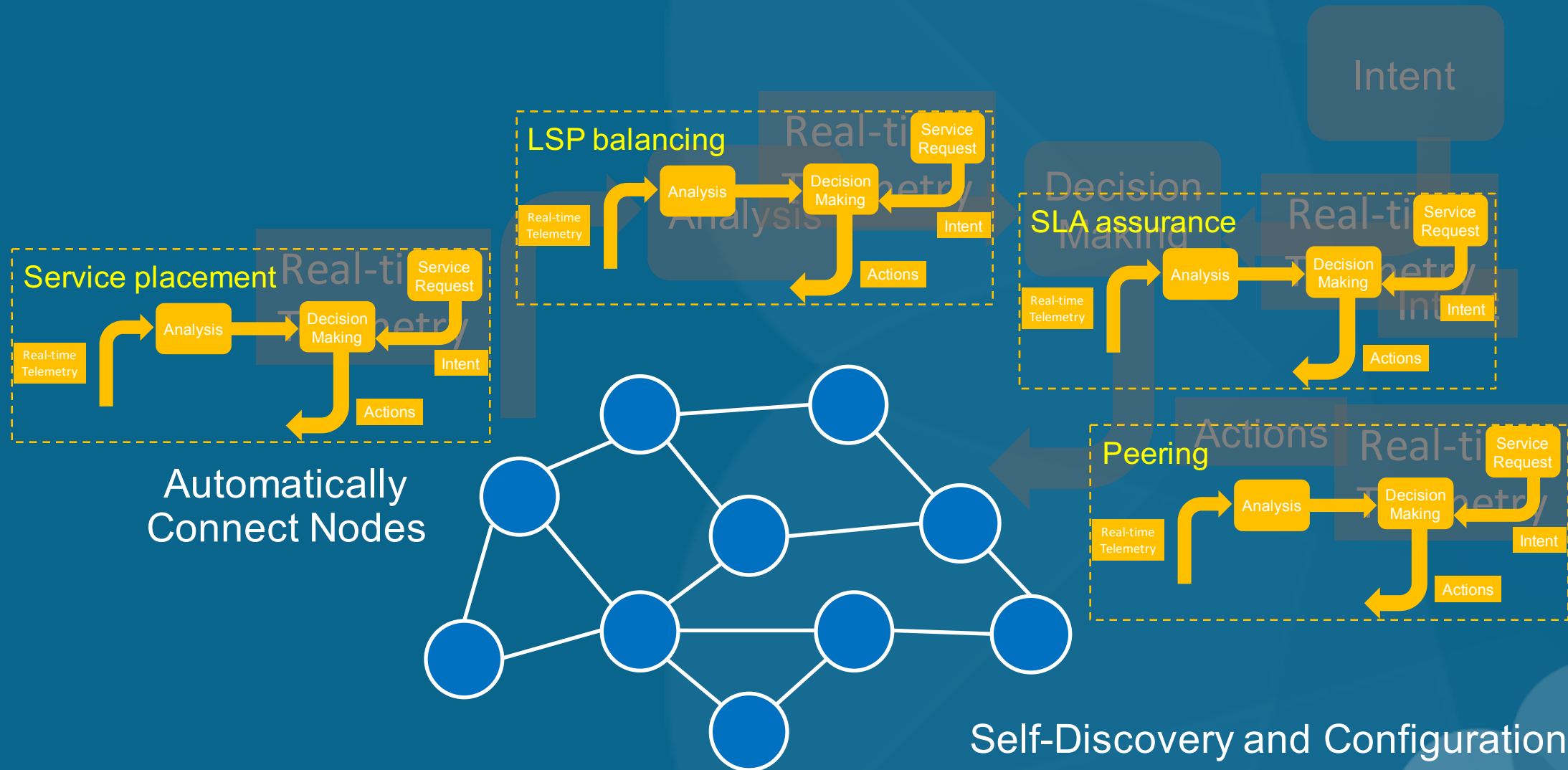
# Architecture of the Self-Driving Network



# Implementing the Self-Driving Network



# Robotized Functions in the Self-Driving Network





# FIRST ROBOT: SERVICE PLACEMENT

which device should offer a given service?

- 1 Specify Service Intent Don't worry about where it will be
- 2 Where best to place the service? Let the controller work this out
- 3 Things change: is placement still optimal? Streaming real-time data
- 4 Service Motion: move service to a new location Update service in real-time

Break the mold! Update service placement often, to keep it optimal

# ANALOGY: Compute Orchestration vs Service Orchestration

OLD: Same (or very similar) servers running **dedicated** apps



Finance



DB



Web



Apps

OLD: Same (or very similar) routers running **dedicated** services



BNG



CMTS



BizPE



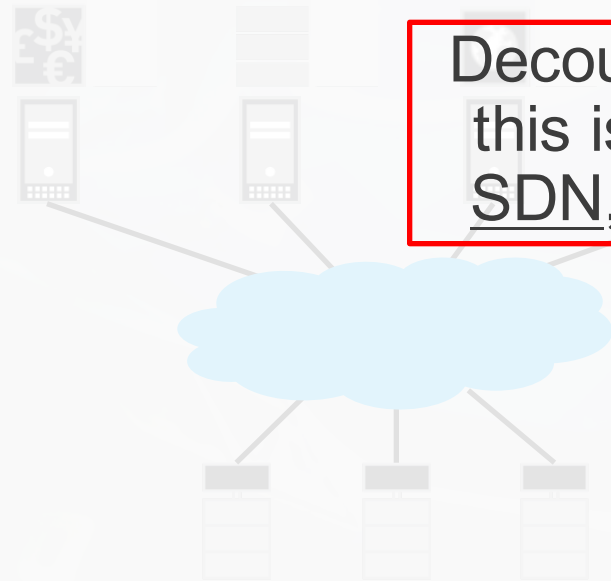
Peering

# ANALOGY: Compute Orchestration vs Service Orchestration

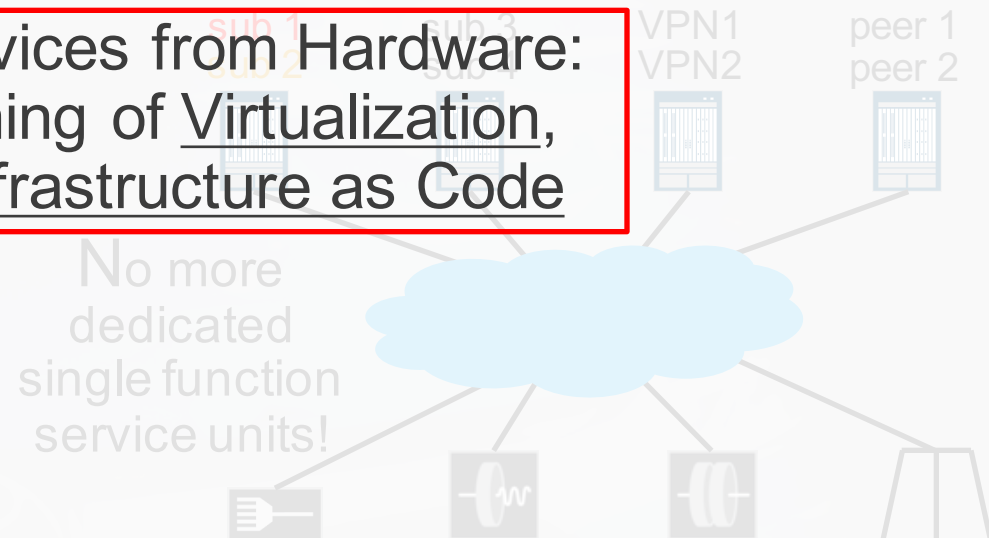
NEW: Apps decoupled from servers;  
storage available to all servers;  
servers are now identical

NEW: Services are decoupled from routers;  
access devices available to all routers;  
routers are now identical

Decoupling Apps/Services from Hardware:  
this is the True Meaning of Virtualization,  
SDN, NFV, Agility, Infrastructure as Code



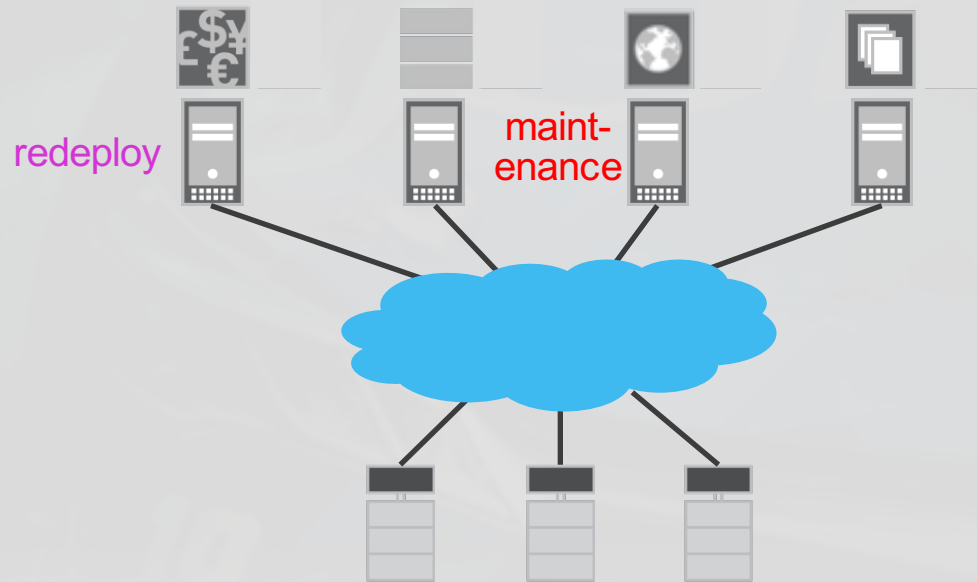
No more  
dedicated  
single function  
servers!



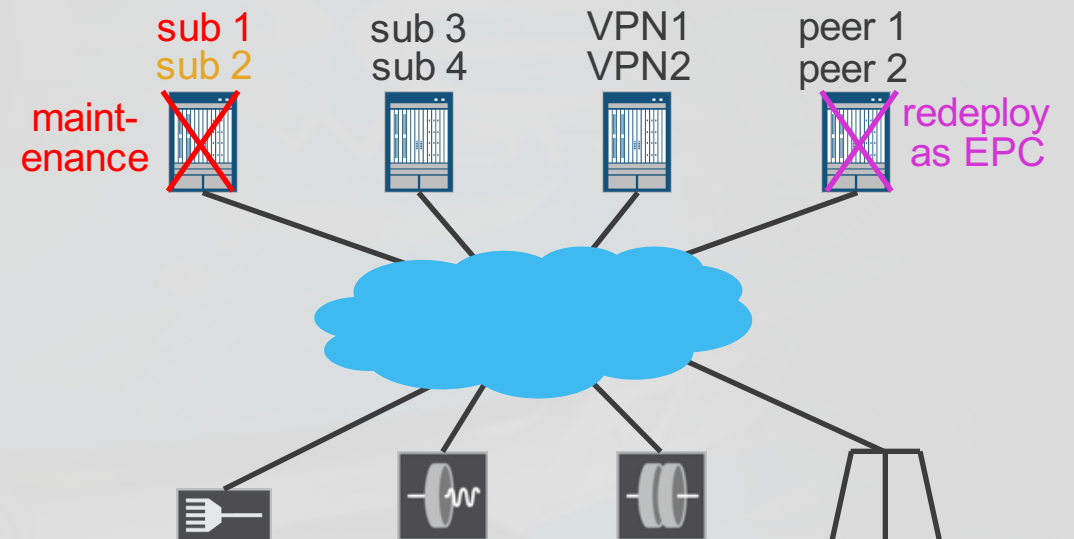
No more  
dedicated  
single function  
service units!

# ANALOGY: Compute Orchestration vs Service Orchestration

NOW POSSIBLE: “vMotion” of individual apps across servers;  
app placement is now a thing



NOW POSSIBLE: “SMotion” of individual services across routers;  
service placement is now a thing



# Peer Bot

## Simplifying Peering Across Internet Exchange

### Business Goals

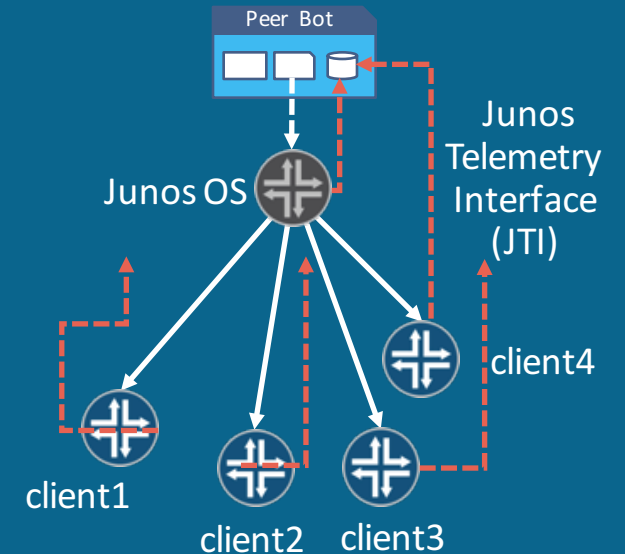
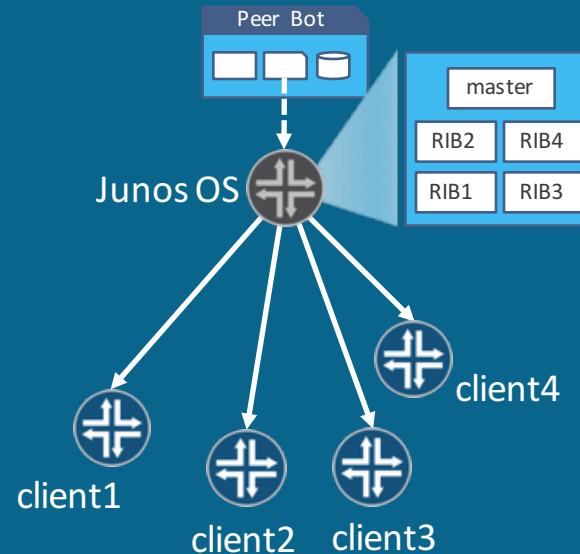
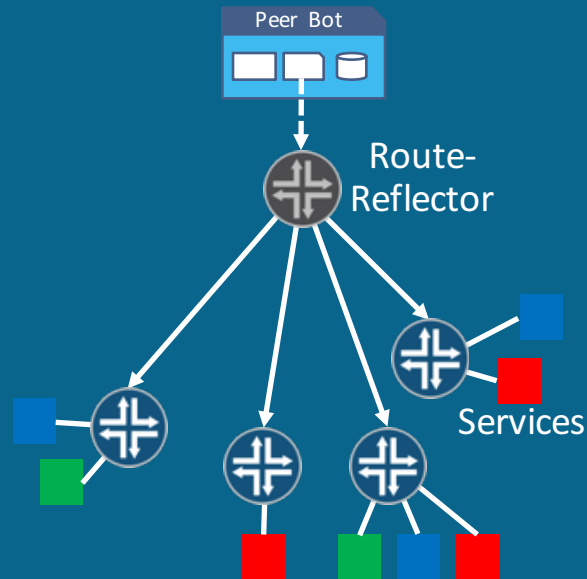
- Optimize Peering costs and application experience

### Customer Requirements

- Seamless Internet Exchange Peering Experience
- On-Demand Scaling and Interconnection
- Support Self-Care Portal
- Design, Build and Operate World-class Networks

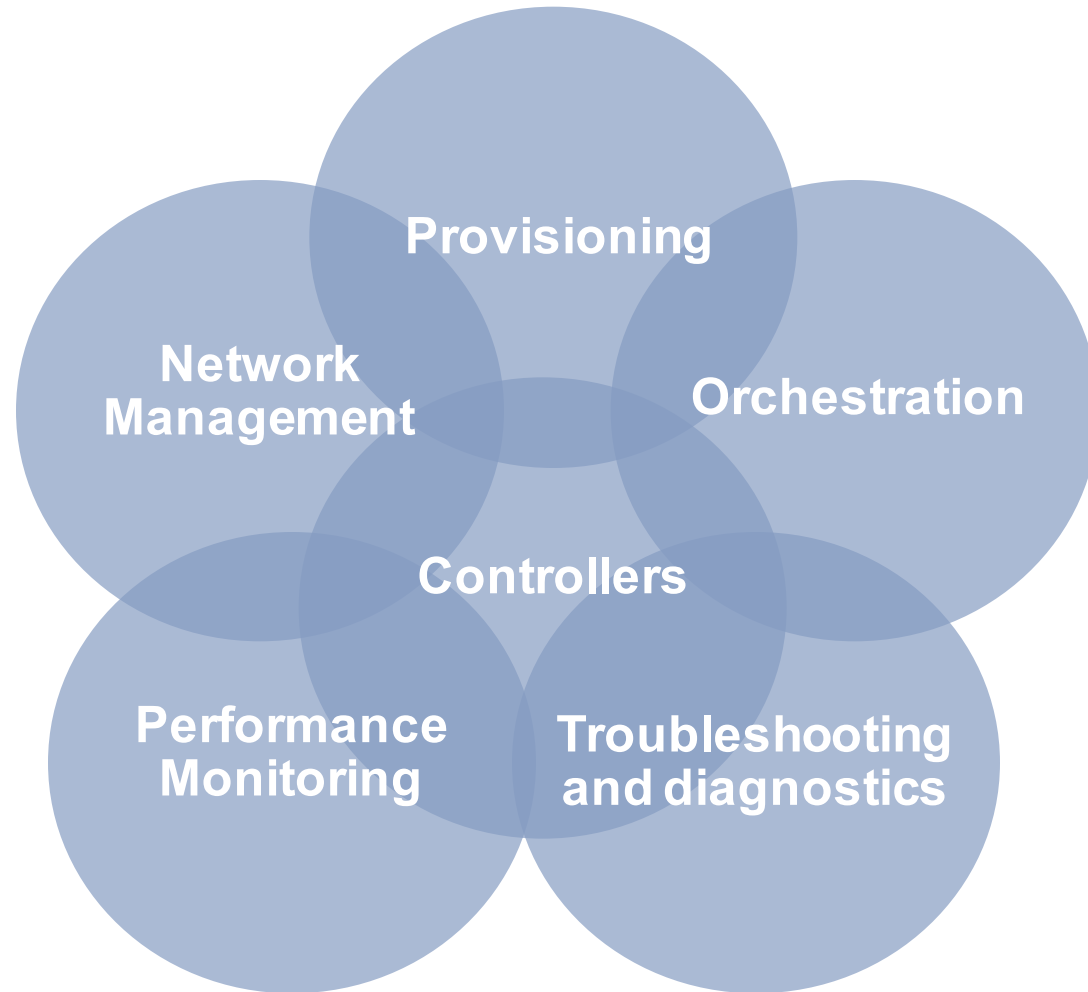
### Peer Robot Benefits

- Seamless Add, Modify, and Remove Peering Points
- Dynamically Establish Peering Policy
- Simplify Network Operations by as much as 800%
  - Adding a new peer 8x faster than via CLI
  - Eliminate complex policy enforcement factorially (N!)
  - View the number of peering routes and bandwidth in real-time



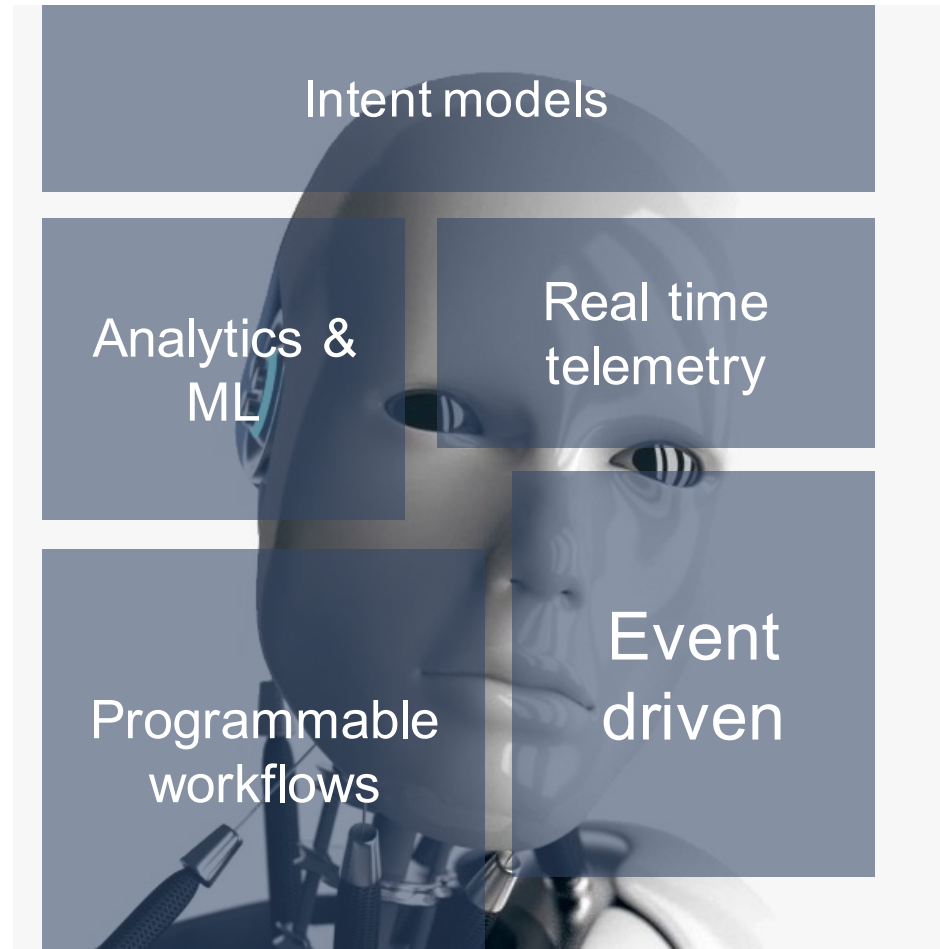
# Blurring frontiers...in the Self-Driving Network

Today's network and service management tools



From network management applications ...

Key new attributes



... into Network Robots



# Conclusion

A Self-Driving Network may seem a hard (nearly impossible!) task

1. Specify requirements declaratively as intent
2. Divide and conquer – break it down to manageable pieces

Roboticizing a function enables new capabilities

- Automating service placement gives you “S-Motion”

Roboticizing peering dramatically reduces complexity

- The peer robot makes peering dynamic and responsive

# Thank you

Visit our booth to see  
the peer robot demo!